

SPARCS tool for GEO S/C charging analysis : Brief presentation and planned evolutions

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- ☐ **Brief presentation of SPARCS (SPAce chaRging Software)**
- ☐ **Planned evolutions**

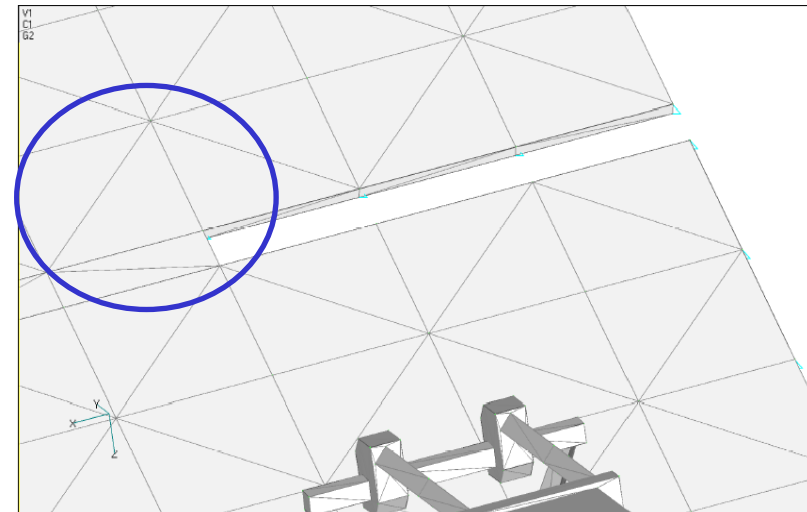
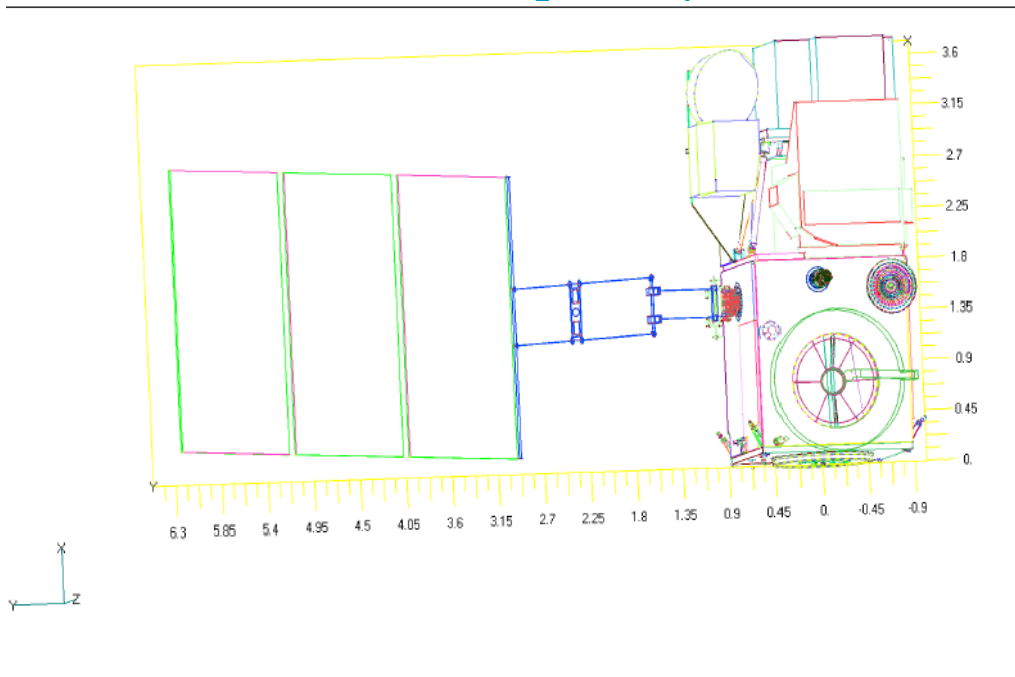
Industrial needs and goals (2001/2002)

- Perform analysis for external charging for GEO/GTO orbits
 - Mandatory for ESD analysis on telecommunication satellites
- Quality
 - Accuracy of computation shall be guaranteed either by comparison with
 - existing software (NASCAP 2K, 2004) and analytical test cases (sphere)
 - test results
 - Satellite modeling directly from CAD definition
- Cost
 - Maximum use of available tools in Thales Alenia Space
 - Time computation shall be limited
 - **The tool shall be easy to take in hand and to maintain**
- Delay
 - A standard telecommunication satellite analysis shall be performed in 3 weeks
- Specific constraints
 - Availability of tools : American tools are submitted to export limitations and SPIS was not yet ready to be used by engineers in an industrial process

■ SPARCS pre-processing (1)

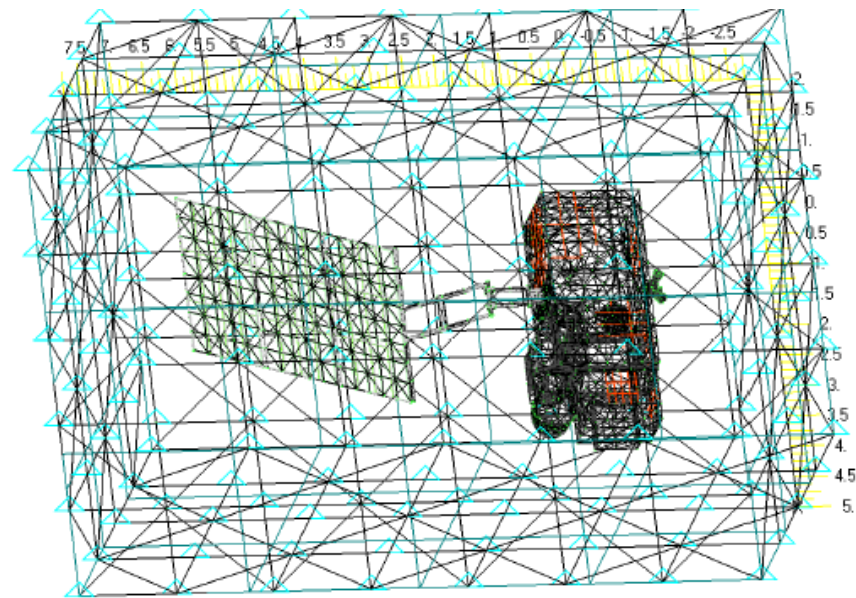
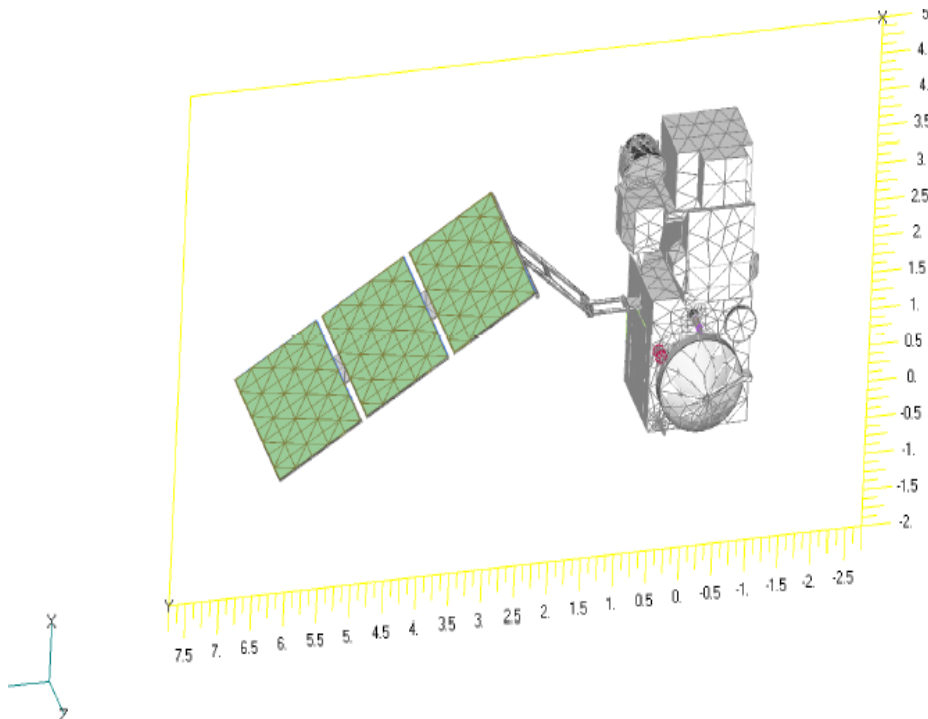
■ Satellite modeling directly from CAD

- Import of CAD file in FEMAP for meshing : .MODEL, IGES or STEP AP203
- Connect all surfaces and attach them material properties and BC
- Retouching some parts of the model (rotation of solar array for different config)



■ SPARCS pre-processing (2)

- Satellite surfaces and surrounding plasma is meshed using automated process (unstructured mesh)
 - 2D triangles on S/C surfaces and on the surrounding box ("infinity" BC)
 - 3D tetrahedrons around satellite
 - Possibility to use FEMAP, PATRAN or GMSH



■ SPARCS methods in brief

■ GEO approximation

- $\lambda_D \gg L$, collisions and B effect neglected

■ S/C is approximated as a perfect conductor partially covered with very thin layer of dielectric materials

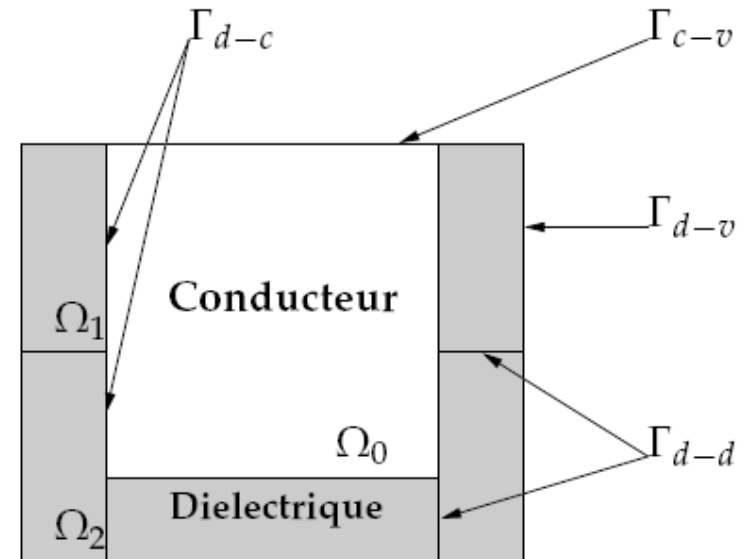
■ Single or Double Maxwellian dist. for space plasma (ions & electrons)

■ Resolution of Vlasov-Poisson problem in the computational domain i-e in the volume between S/C external surfaces and the artificial infinite boundary

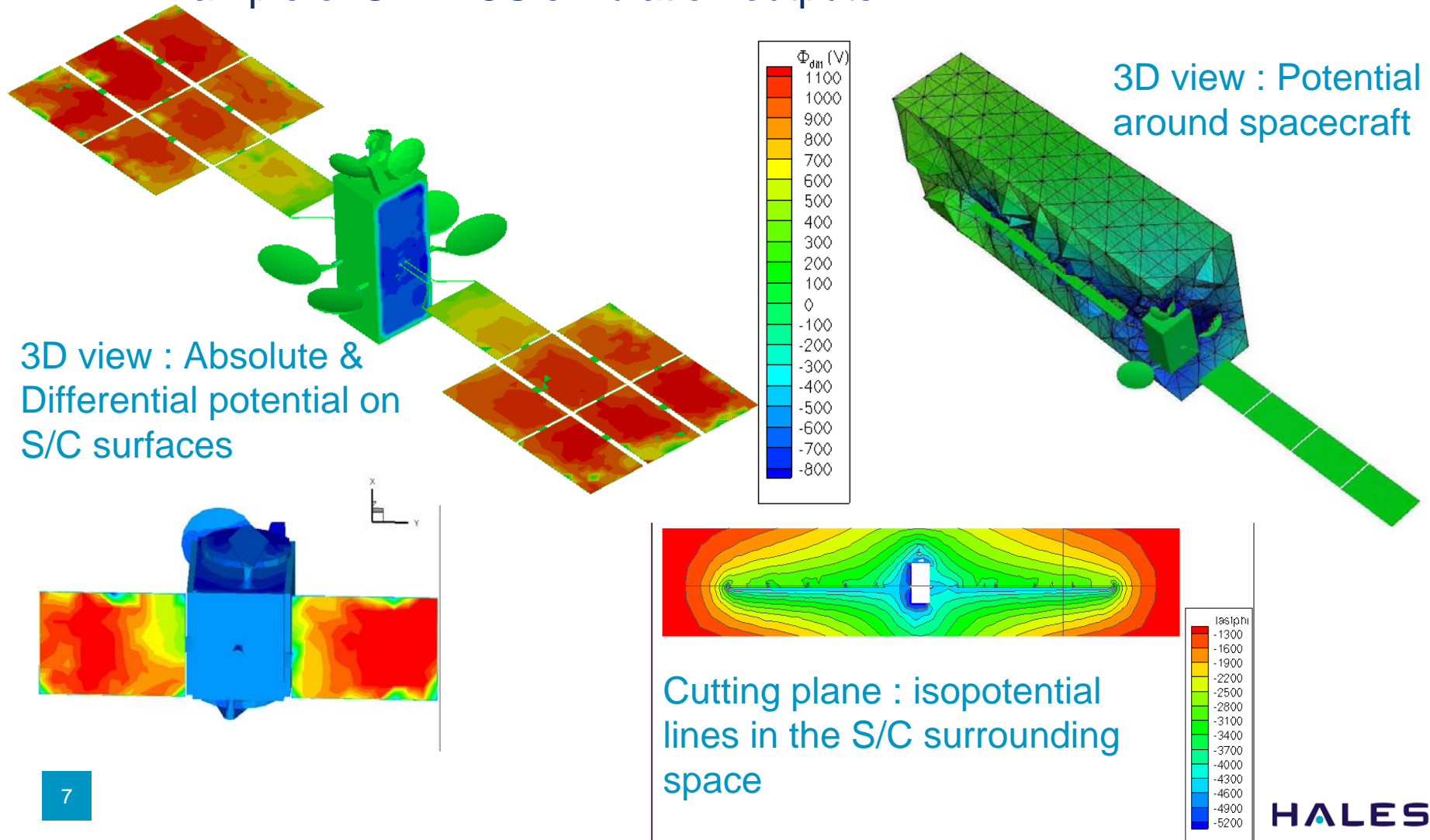
- P1 Finite elements (surfaces) and infinite elements
- Transient computation of the S/C absolute potential Φ_{abs} (conductor frame) and differential potential Φ_{diff} on external S/C dielectric surfaces
- On the basis of calculation and balance of primary (plasma ions and electrons, bulk conduction) and secondary currents (ion and electron induced secondary emission, photo-emission, back scattering, recollection)

● Use of back-tracking algorithm for solving collected currents

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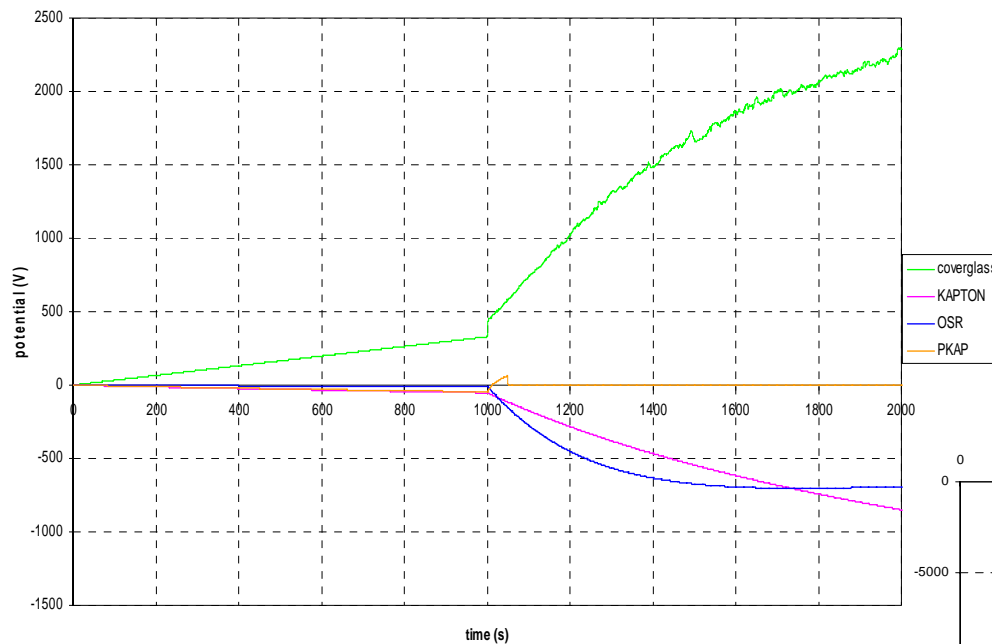
■ Example of SPARCS simulation outputs



■ Example of SPARCS results : transient simulation

■ Spacebus during eclipse & out of eclipse

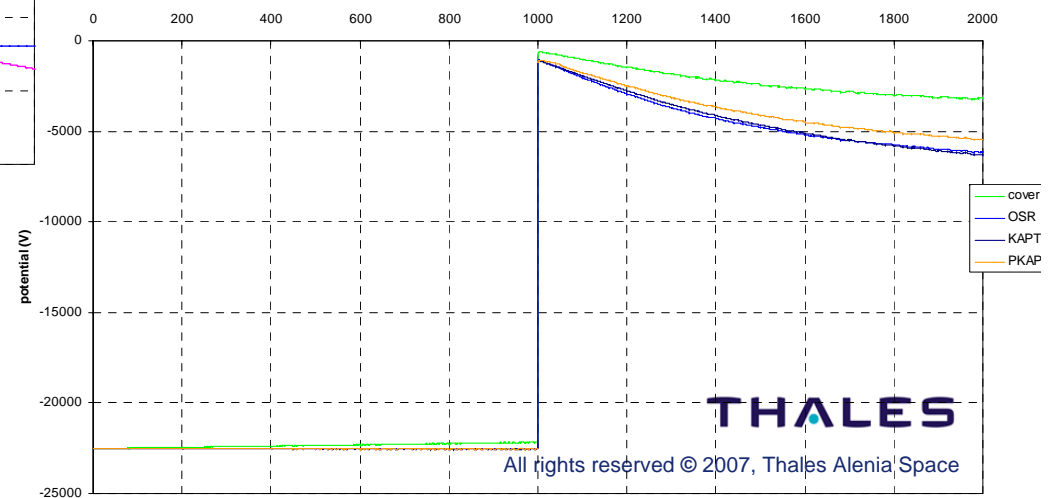
Spacebus eclipse & out of eclipse - differential potentials



2D plot vs time of Φ_{ABS} and Φ_{diff} on S/C surfaces :

Ex : Max Φ_{diff} , Min Φ_{diff} , Φ_{diff} at user defined probe points

Spacebus eclipse & out of eclipse - absolute potentials - SPARCS



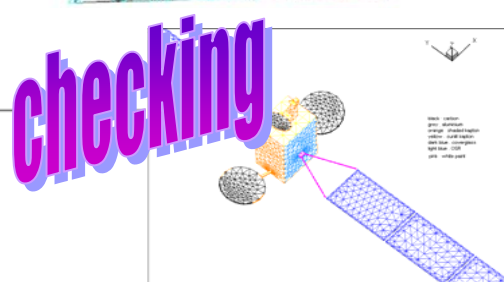
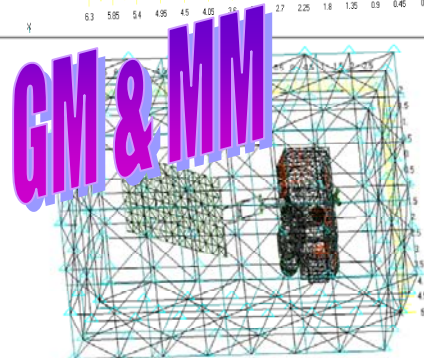
Integration in an end-to-end charging analysis tool

■ Objective

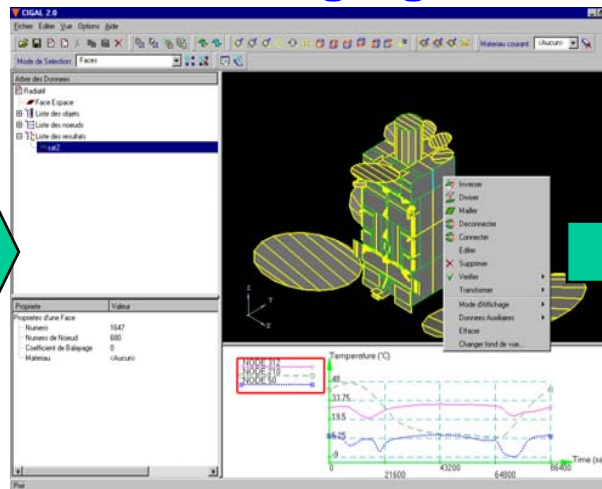
- Today SPARCS is interfaced with COTS s/w for pre and post processing, and it causes some problems
 - Reducing cost by using license free existing s/w
 - Make handling and external distribution more easy (for use or for development)
 - Simplify even more the user process
 - Add some new capabilities (e.g more assisted retouch of CAD geometriy, 3D transient animation of results, ...)
- Need for an integrated end-to-end s/w chain

■ Project 2010

- Development of an integrated S/C charging simulation chain in CIGAL2 application
 - Low cost since CIGAL2 is actually the TAS pre/post processing tool for thermal analysis
- Technical requirement and URD is ready
- Convergence between tools : multidisciplinary tool (Thermal / Space Environment)



CIGAL S/C charging module

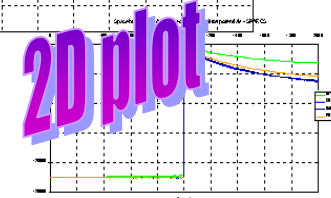
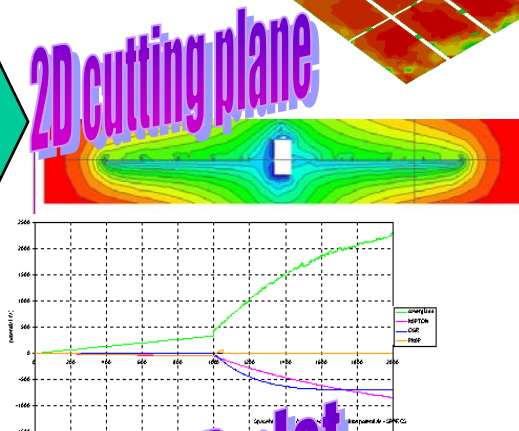
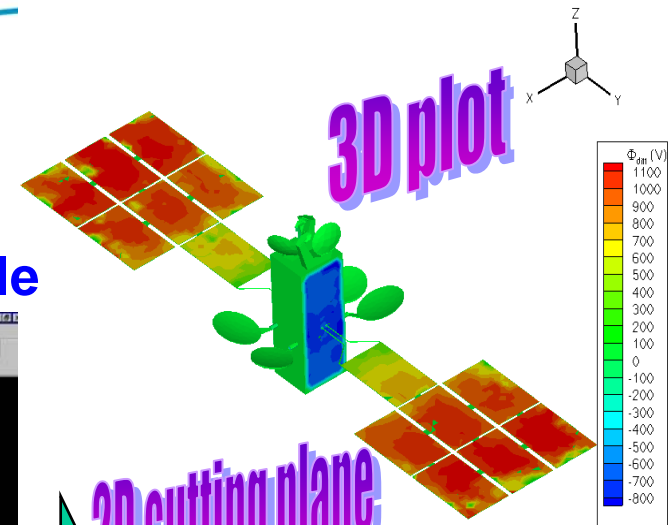


Inputs :

- Geometry/FEM mesh
- Boundary conditions (electron/ion distribution, ...)
- Materials
- Run definition data

Outputs :

- Absolute and differential electric potential on SC surfaces (3D & 2D plot)
- Primary and secondary currents
- Iso-potential lines around S/C



- Parallelisation using graphic card capability
 - Today SPARCS is parallelized for cluster of up to 8 processors (Open MP)
 - We intend to extend this capability by using graphic card vectorized computation process
 - Should be very interesting for back-trajectory algorithm which constitutes the major part of CPU time (Vlasov solver)
 - Goal : Reduction of CPU time for charging simulation runs
 - For a typical simulation of large telecom S/C : ~ 1500 sec of transient simulation
 - Pass from 4- 8 h to less than 1h
- Comparison with SPIS for typical telecom S/C charging analysis
 - Project for 2010 (R&T CNES proposal) : results, handling & user-friendliness , CPU time, modelling & post-pro capability
- Need to simulate S/C charging with electrical propulsion
 - Project to test SPIS capability in 2010 (R&T CNES proposal)
- Multipotential simulation (nearly achieved)
 - Possibility to define and solve different reference potential
 - Eg : Allow to fix potential on each solar cell of SA
- Adaptative time step for dynamic solver
- Better model for SEE